RHODE ISLAND UNIV KINGSTON DEPT OF MATHEMATICS OPTIMIZATION OF MULTICHANNEL PROCESSING.(U) SEP 80 O SHISHA F/G 9/3 AD-A091 987 AFOSR-77-3174 AFOSR-TR-80-1146 NL UNCLASSIFIED 1000 A A35 35 END

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FINAL REPORT

ON

GRANT AFOSR-77-3174

OPTIMIZATION OF MULTICHANNEL PROCESSING

SEPTEMBER 1980



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(18) REPORT DOCUMENTATION PAGE	READ INSTRUCTIONS BEFORE COMPLETING FORM
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OPTIMIZATION OF MULTICHANNEL PROCESSING	FINAL KLOT.
AUTHOR(a)	8. CONTRACT OR GRANT NUMBER(a)
Professor Oved Shisha	AFOSR-77-3174
PERFORMING ORGANIZATION NAME AND ADDRESS	10. PROGRAM ELEMENT, PROJECT, TASK
University of Rhode Island, Department of Mathematics, Kingston, R. I. 02881	61102F/2304/A3/
CONTROLLING OFFICE NAME AND ADDRESS Air Force Office of Scientific Research/NM	SEPTEMBER 4980
Bolling AFB, Washington, DC 20332	13. A PAGES OF PAGES
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better results than the optimum conventional filter.

The complex subset selection method is also applied to estimation of the frequencies of sinusoids in the presence of noise. A windowing technique is introduced to increase the efficiency and accuracy of the algorithm for frequency estimates. The results are compared with Cramer-Rao bounds.

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- I. Introduction. During the contract period substantial progress was made on three basic problem areas:
 - (1) The partial basis problem.
 - (2) Least squares approximation with restricted range.
 - (3) Mixed norm approximation.

In sections II, III, IV, we will discuss some of our work in each of these areas. In section V some other results are discussed.

II. The Partial Basis Problem. This problem was formulated by us in 1975 as a generalization of a problem of placing antenna elements optimally in a line array; independently, G. G. Lorentz studied a special case [11]. The problem has received considerable attention from researchers in recent years and elegant results have been obtained by us and others. This should prove to be a fruitful area for further investigation.

The partial basis problem can be stated in its general form as follows. Let X be a normed linear space, let f, h_0, \cdots, h_{N-1} belong to X and let n be an integer, $1 \le n < N$. For every sequence $\mu = \left\{\mu_k\right\}_{k=1}^n \quad \text{of integers, with } 0 \le \mu_1 < \cdots < \mu_n \le N-1 \text{ , consider } e(\mu) = \min_{\substack{c_1, \cdots, c_n}} \| f = \sum_{k=1}^n c_k h_{\mu_k} \| .$

The problem is to minimize $e(\mu)$; it is of particular interest when X is one of the standard function spaces. The main results of [7] gives sufficient conditions for the "tail" h_{N-n} , \cdots , h_{N-1} , to be the unique best partial basis of size n. Typical theorems are:

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Theorem 1. Let $0 < a < b < \infty$ and let N,n be integers with $1 \le n < N$. Let f be a real function, continuous in [a,b] and assume that, for $k = 0, 1, \cdots, n, (x^{k-N}f)^{(k)}$ exists and is ≥ 0 in (a,b), with strict inequality there for k = n - 1 and k = n. Let $0 \le \mu_1 < \cdots < \mu_n \le N-1$ be integers such that $\{\mu_1, \cdots, \mu_n\} \ne \{N-n, \cdots, N-1\}$. Let $1 \le p \le \infty$.

Theorem 2. Let $0 \le \alpha_{N-1} < \alpha_{N-2} < \cdots < \alpha_0 < \frac{1}{2}$ and let $1 \le n < N$, n pict an integer. Let f be a real function with $f^{(2k+1)}(0) = 0$, $k = 0, \cdots, N-1$, and $f^{(2k)}(x) > 0$ on $(0,\pi]$ for $k = 0,1,\cdots,N$. Assume $f^{(2N-1)}(x)$ is continuous from the right at 0. Let $0 \le \mu_1 < \cdots < \mu_n \le N-1$ be integers such that $\{\mu_1, \cdots, \mu_n\} \ne \{N-n, \cdots, N-1\}$. Let $1 \le p \le \infty$. Then

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$$\min_{\substack{\mathbf{c}_{\mathbf{k}} \text{real}}} \| \mathbf{f}(\mathbf{x}) - \sum_{k=N-n}^{N-1} c_{k} \cos \alpha_{k} \mathbf{x} \|_{\mathbf{L}^{\mathbf{P}}(0,\pi)} <$$

$$\min_{\substack{\mathbf{c}_{\mathbf{k}} \text{real}}} \| \mathbf{f}(\mathbf{x}) - \sum_{k=1}^{n} c_{k} \cos \alpha_{\mu} \mathbf{x} \|_{\mathbf{L}^{\mathbf{P}}(0,\pi)}$$

The theory of Tchebycheff systems is important for partial basis results and [7] contains contributions to this theory. A typical theorem:

Theorem 3. Let $0 < \alpha_0 < \cdots < \alpha_n$. Then $\cos \alpha_n x \ , \ \sin \alpha_0 x \ , \ -\cos \alpha_1 x \ , \ -\sin \alpha_1 x \ , \cdots \ , \ (-1)^n \cos \alpha_n x \ , (-1)^n \sin \alpha_n x$ is an extended complete Tchebycheff system on $[0, \pi]$ if and only if $\alpha_n < 1/2 \ .$

Elegant results have been obtained by Lewis, Pinkus, and Shisha [9] giving sufficient conditions for the "head" h_0, \cdots, h_{n-1} to be the unique best partial basis of size n . Perhaps the most striking result is this:

Theorem 4. Let $0 < a < b < \infty$, $1 \le n < N$, f continuous and positive on [a, b], $(-1)^k$ $f^{(k)}(x) > 0$ for a < x < b, $k = 1, \cdots, n$ and $1 \le p \le \infty$. Then for $s = 1, \dots, n+1$ any subsequence of length s of $f, 1, x, \cdots, x^{N-1}$ is a Tchebycheff system on [a, b] and

$$\min_{\substack{c_k \text{real}}} ||f(x) - \sum_{k=0}^{n-1} c_k x^k||_{L^p(a, b)} < \min_{\substack{c_k \text{real}}} ||f(x) - \sum_{k=1}^{n} c_k x^k||_{L^p(a, b)}$$

whenever $0 \le \mu_1 < \cdots < \mu_n \le N-1$ and $\{\mu_1, \cdots, \mu_n\} \ne \{0, 1, \cdots, n-1\}$.

The classical completely monotonic functions satisfy the hypotheses of Theorem 4 and hence are best approximated by $1,x,\cdots,x^{n-1}$. Examples are $f(x)=e^{-CX}$, c>0, $[a,b]\subset (0,\infty)$ and $f(x)=x^{-M}$, M= positive integer, $[a,b]\subset (0,\infty)$.

The problem of finding the best partial basis computationally, for situations where theorems of the above type are inapplicable, was studied in [1]. An algorithm was presented, generalizing an algorithm of Hocking and Leslie [12], and a computer program was written and tested on some numerical examples. Also a theorem givin continuous dependence of a best approximation on the basis functions was given in [1]. This algorithm

was extended to complex-valued basis functions and used to design finite impulse response digital filters and to estimate frequencies of sinusoids in the presence of noise; cf. [4].

III. Least Squares Approximation with Restricted Range. This problem can be formulated as follow:

minimize
$$\int_{a}^{b} [f(x) - h(x)]^{2} dx$$

subject to $\ell(x) \le p(x) \le u(x)$ for all x in a set I. This includes the problem of positive approximation (where $p(x) \ge 0$ is required) which has been studied by several investigators ([13], [14]).

The following characterization theorem has been obtained (under certain hypotheses on H, f, l, u, and I which will not be specified here):

The approxi ation h^* in H is a solution of the least squares restricted range problem if and only if $l \le h^* \le u$ on I and there exists points x_1, \dots, x_k in I and constants $\sigma_1, \dots, \sigma_k$ such that:

(i) For
$$i = 1, \dots, k$$
, either $h^*(x_i) = \ell(x_i)$
or $h^*(x_i) = u(x_i)$

(ii) sign
$$\sigma_i = \begin{cases} +1 & \text{if } h^*(x_i) = u(x_i) \\ -1 & \text{if } h^*(x_i) = \ell(x_i) \end{cases}$$

(iii)
$$\int_{a}^{b} (f-h^*)h_{j} = \sum_{i=1}^{k} \sigma_{i} h_{j} (t_{i}), j = 1, \dots, n$$
.

(Here h_1, \dots, h_n is a basis for the set of approximations) .

Computational algorithms of the Remes type have been formulated, convergence proofs obtained, and numerical examples solved in [6], [8].

IV. Mixed Norm Approximation. In designing beam patterns for antenna arrays and in designing the frequency response of a digital filter, one may wish to use different criteria of approximation for different intervals. For example, one might use a uniform norm

$$\max_{x \text{ in } I_1} |f(x) - p(x)|$$

in the passband interval I_1 and a weighted least squares norm

$$\left(\int_{I_2} w(x) |f(x) - p(x)|^2 dx\right)^{1/2}$$

in the stopband interval \mathbf{I}_2 . Two possible approaches are:

- (i) minimize $\int_{I_2} w(x) |f(x)-p(x)|^2$ subject to $-\varepsilon \le f(x)-p(x) \le \varepsilon$ for all x in I_1 ;
 and
- (ii) minimize $\{\lambda \max_{x \text{ in } I_1} |f(x)-p(x)|^2 + (1-\lambda) \int_{I_2} w(x) |f(x)-p(x)|^2 dx \}$

where $0 < \lambda < 1$. The "mixed norm" problem (ii) can be converted to a quadratic programming problem, and solved; cf [2]. It is shown in [2] that, for f(x) of a certain type, (i) and (ii) are

equivalent in the following sense: If $p_{\lambda}(x)$ solves the problem (ii) for some λ , $0 < \lambda < 1$, then there exists an $\varepsilon > 0$ such that $p_{\lambda}(x)$ solves problem (i). Conversely, if $p_{\varepsilon}(x)$ solves (i) for some ε , there exists λ , $0 < \lambda < 1$ such that $p_{\varepsilon}(x)$ solves (ii). It is also shown that mixed norm approximation is related to vectorial approximation, developed by A. Bacopoulos and others [15]. In [6] the "mixed norm" in (ii) above is generalized to $\lambda^r ||f-p||_1^r + (1-\lambda)^r ||f-p||_2^r$ where $1 \le r$ and $||f-p||_1^r + ||f-p||_1^r + ||f-p||_2^r$ where $1 \le r$ and $||f-p||_1^r + ||f-p||_1^r +$

V. Other Results. In this section we discuss other work partially supported by the Grant, namely [10] and [5]. Let $-\infty < a < 0 < b < \infty$, and f a real function, continuous on [a, b] but not a polynomial there. Given integers k, n

(1)
$$E_n(f) = \min \max_{a \le x \le b} |f(x) - p_n(x)|$$

denote

where the minimum is taken over polynomials of degree at most n. Let $E_n^k(f)$ denote the right hand side of (1) where the minimum is taken over all polynomials of degree at most n whose coefficient of x^k is 0. It follows from work in [17], [18] that if $f^{(k)}$ exists and satisfies a Lipschitz condition of order α (0< α <1) throughout [a,b] and if

 $f^{(k)}(0) \neq 0$ then there exists a positive constant A_n such that

(2)
$$\frac{E_n^{(k)}(f)}{E_n^{(f)}} \ge A_k^{\alpha}$$
, $n = 0, 1, \cdots$.

In [10] a converse theorem has been obtained which essentially states that if inequality (2) holds, then $f^{(k)}$ exists and satisfies a Lipschitz condition of order α on each closed interval [a',b'] with a < a' < b' < b. Hence a remarkable theorem is obtained identifying a certain smoothness of f with the growth of $\frac{E_n^{(k)}}{E_n^{(k)}}$.

Note that this theorem could be considered a "partial basis" result of type described in Section II.

In conclusion we mention briefly [5] where Muntz-type closure theorems are obtained for sequences of the form

$$\left\{w(t)t^{\alpha}k\right\}_{k=1}^{\infty}$$
 on unbounded intervals.

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